

On the Decidability of Reachability in Linear Time-Invariant Systems

Nathanaël Fijalkow, Joël Ouaknine, Amaury Pouly, João Sousa-Pinto, James Worrell

CNRS, IRIF, Université Paris Diderot

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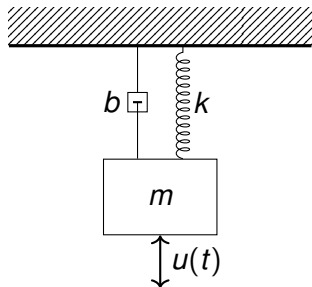
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Example : mass-spring-damper system



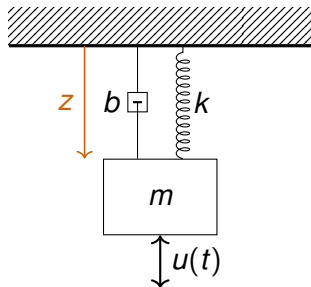
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Equation of motion :

$$mz'' = -kz - bz' + mg + u$$

Model with external input $u(t)$

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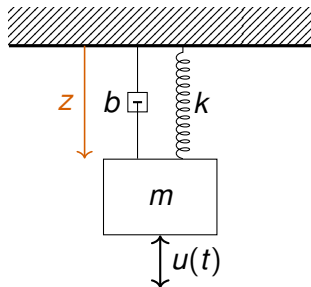
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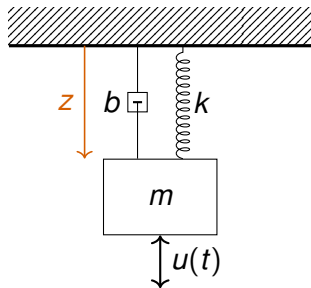
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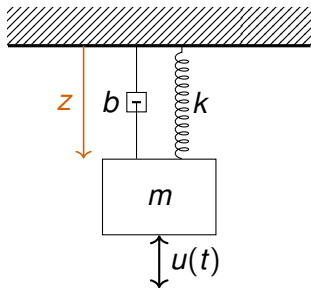
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Model with external input $u(t)$

→ Linear time invariant system

$$X' = AX + Bu$$

with some constraints on u .

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Linear dynamical systems

Discrete case

$$x(n+1) = Ax(n)$$

- ▶ biology,
- ▶ software verification,
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- ▶ combinatorics,
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Continuous case

$$x'(t) = Ax(t)$$

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Typical questions

- ▶ reachability
- ▶ safety

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The problem

LTI-REACHABILITY

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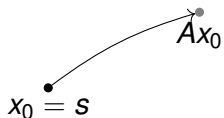
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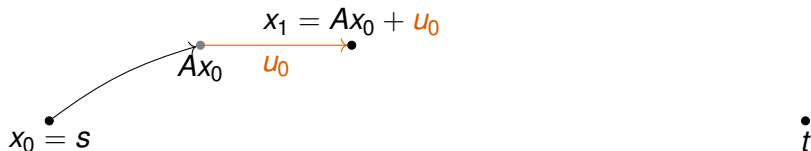
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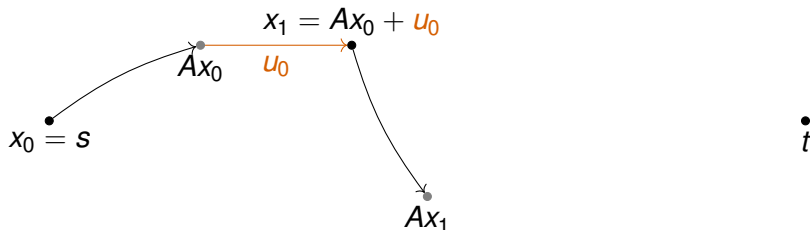
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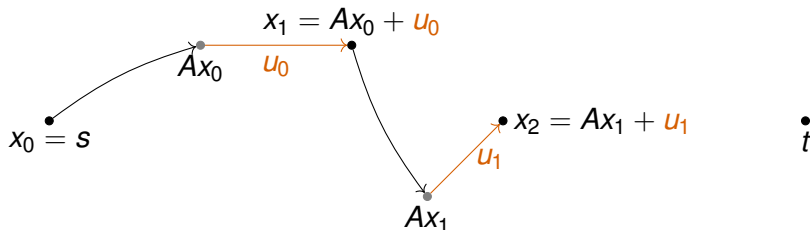
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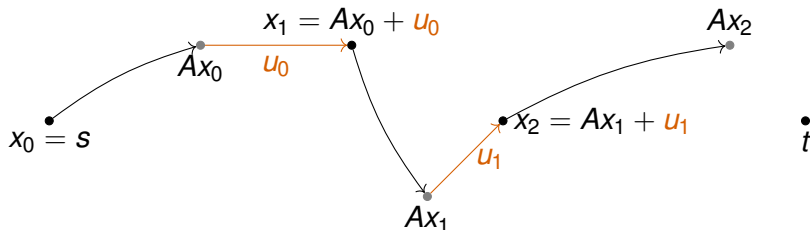
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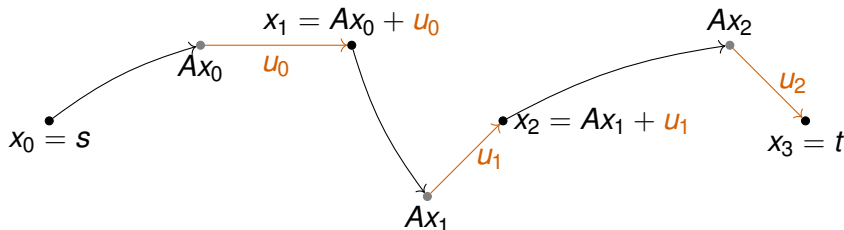
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Almost no exact results for other classes of U in particular when U is bounded (which is the most natural case).

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Study the impact of the control set on the hardness of reachability

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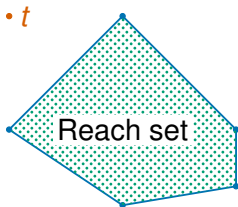
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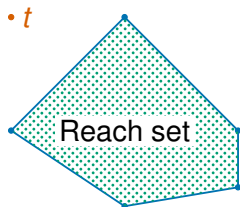


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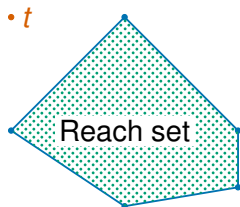


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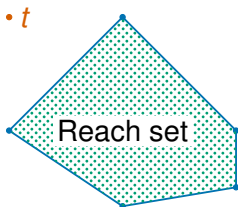
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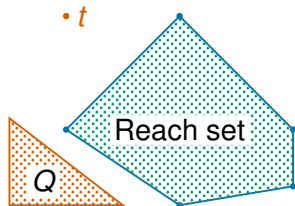
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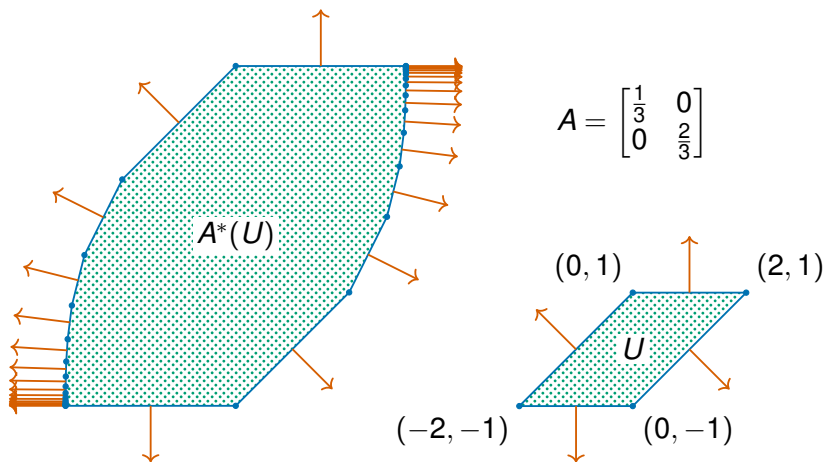
Remark : in fact we can decide reachability to a convex polytope Q .



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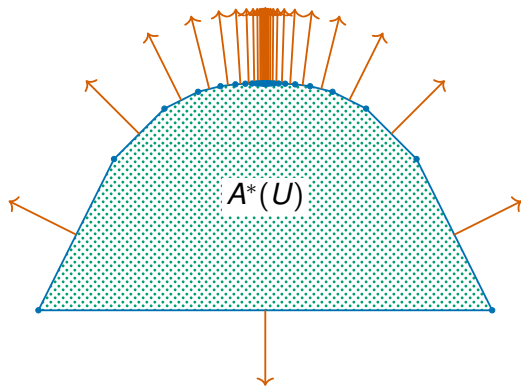
Why is this problem hard

The reachable set $A^*(U)$ can have **infinitely** many faces.

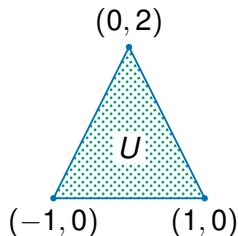


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The reachable set $A^*(U)$ can have **faces of lower dimension** : the "top" extreme point does not belong to any facet.



$$A = \begin{bmatrix} \frac{2}{3} & 0 \\ 0 & \frac{1}{3} \end{bmatrix}$$



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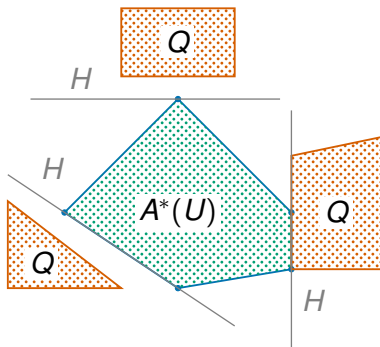
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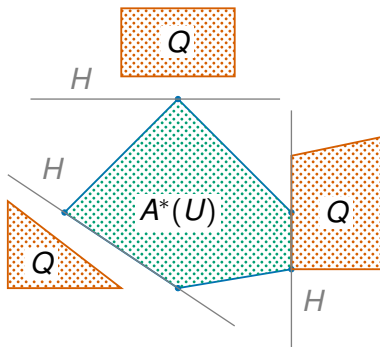
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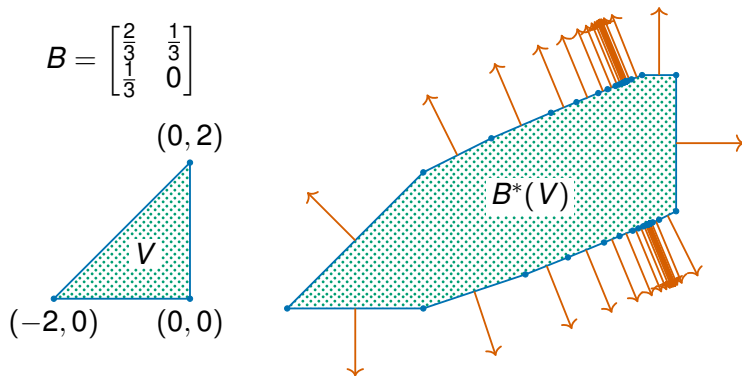
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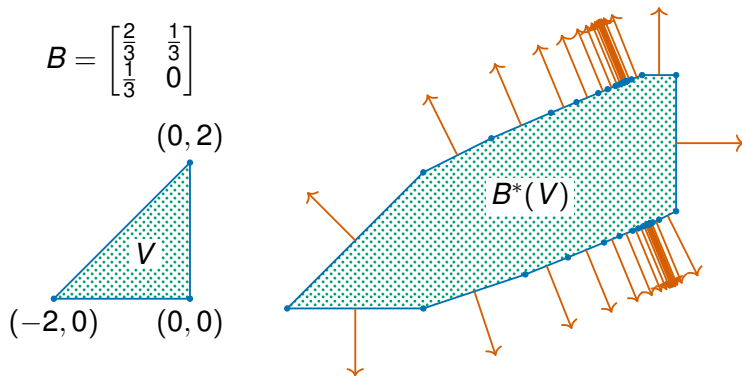
Further difficulty : a separating hyperplane may not be supported by a facet of either $A^*(U)$ or Q .

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Theorem (Non-reachable instances)

There is a separating hyperplane with algebraic coefficients.

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Future work : continuous case $x'(t) = Ax(t) + u(t)$

Backup slides